

# ***U.S. PATENT APPLICATION***

***Inventor(s):*** Mitsuyuki KOBAYASHI  
Masao KANO  
Koichi INAGAKI

***Invention:*** LEAK CHECK DEVICE FOR EVAPORATED FUEL PURGE SYSTEM

***NIXON & VANDERHYE P.C.  
ATTORNEYS AT LAW  
1100 NORTH GLEBE ROAD, 8<sup>TH</sup> FLOOR  
ARLINGTON, VIRGINIA 22201-4714  
(703) 816-4000  
Facsimile (703) 816-4100***



13281 U.S.PTO  
030404

## LEAK CHECK DEVICE FOR EVAPORATED FUEL PURGE SYSTEM

### CROSS REFERENCE TO RELATED APPLICATION

This application is based on and incorporates herein  
5 by reference Japanese Patent Application No. 2003-57552 filed  
on March 4, 2003.

### FIELD OF THE INVENTION

The present invention relates to a leak check device  
10 for evaporated fuel purge system.

### BACKGROUND OF THE INVENTION

An evaporated fuel purge system includes, for example, a fuel tank of an internal combustion engine, a canister, and  
15 a purge control valve. This evaporated fuel purge is so designed that evaporated fuel produced in the fuel tank is temporarily adsorbed to the canister. The evaporated fuel adsorbed to the canister is taken, together with fresh air introduced through the fresh air inlet in the canister, into  
20 the air intake system of the internal combustion engine through the purge control valve. However, when a crack or the like exists in a pipe or container constituting an evaporated fuel recovery path running from the fuel tank to the purge control valve through the canister, the evaporated fuel leaks to the outside and the effect of preventing the emission of evaporated  
25 fuel cannot be sufficiently attained.

Recently, strict leak check has become mandatory against

evaporated fuel emissions from fuel reservoir systems, such as the fuel tank of the vehicle, into the atmosphere. For this reason, a variety of leak check systems for diagnosing leakage from the evaporated fuel purge system are proposed.

5 According to US Patent 5,890,474 (JP-A-10-90107: Patent Document 1), a module is placed on the atmosphere port side of a canister. In this module, a switchover valve for switching flow paths and a motor pump are connected and integrated with each other. A reference leak is caused by the motor pump with 10 pressure as a result of changing the flow path by the switchover valve. Then, the state of leakage from an evaporated fuel recovery path is compared with the reference leak. More specifically, pressure is alternately applied by the motor pump, for example, to a reference orifice and to the atmosphere port 15 side of the canister, that is, the evaporated fuel recovery path. The reference orifice is for providing leakage reference values established by the California Air Resources Board (CARB) and the Environmental Protection Agency (EPA). At this time, the voltage of the motor pump is measured in the respective cases, 20 and the comparison is made by operation characteristic values, such as current consumption, obtained therefrom.

According to the prior art disclosed in JP-A-11-336619 (Patent Document 2), a detecting device for detecting the state 25 of use of an air conditioner is provided for prevention of erroneous determination due to the influences of the vapor pressure of fuel. A determination value for reference leak is corrected according to the results of detection by the detecting

device. When the air conditioner is in operation, the outdoor temperature is estimated to be high, and the fuel temperature is also considered to be high.

According to the prior art disclosed in JP-A-2000-205056 (Patent Document 3), the driving voltage for a motor pump is changed to shorten time required for diagnosing a leak. Immediately after a start of driving, the motor pump is driven on relatively high voltage to increase the amount of discharging from the motor pump. Thereafter, the voltage is returned to normal voltage to return the amount of discharging to the reference amount of discharging for leak diagnosis.

The above prior arts are not satisfactory. When the supply voltage of a battery or the like for driving a motor pump fluctuates, the driving voltage proportionally fluctuates, which varies the performance of the motor pump itself. For example, when the supply voltage has dropped due to deterioration in a battery, the driving voltage of the electric motor unit constituting the motor pump drops. As a result, the capability of the motor pump to apply pressure is lowered. This decrease in motor pump power takes place not only in pressure pumps which discharge air to apply pressure but also in vacuum pumps which suck air or the like to reduce pressure.

The reference pressure based on a reference orifice and the internal pressure in an evaporated fuel recovery path can be measured using a vacuum pump and compared with each other. The influences of some factors on the accuracy of comparative determination in this case will be described below.

FIG. 11A is a graph plotting pressure change characteristics with low supply voltage, and FIG. 11B is a graph plotting pressure change characteristics with high supply voltage. In these graphs of pressure change characteristics, the horizontal axes show elapsed time and the vertical axes show absolute pressure  $P$ . The elapsed time can be divided into, for example, four sections, section A to section E, in correspondence with the process of leak check. The reference pressure  $P_r$  and the internal pressure in evaporated fuel recovery path are evaluated in sections C and D, respectively. With the lowered supply voltage, illustrated in FIG. 11A, the performance of the vacuum pump degrades.

Accordingly, the reference pressure  $P_r$  approaches the atmospheric pressure  $P_{atm}$ , and the magnitude of the negative pressure of reference pressure is also reduced (section C). Thus, the difference between the reference pressure  $P_r$  obtained by the reference orifice and the atmospheric pressure  $P_{atm}$  is reduced. Therefore, the differences are reduced between three different pressure change characteristics: pressure change characteristics with  $\phi 0.5$  mm which is the same as the size of the hole in the reference orifice; pressure change characteristics with  $\phi$  more than 0.5 mm with which a large leak takes place; and pressure change characteristics without leak. As a result, the accuracy of leak detection for determining in which state of leakage the size of a leaking hole determined from internal pressure change in section D is can be impaired.

With the high supply voltage, as illustrated in FIG.

11B, the reference pressure  $P_r$  deviates from the atmospheric pressure  $P_{atm}$ , and the magnitude of the negative pressure of the reference pressure  $P_r$  is increased (Section C). As a result, the difference between the reference pressure  $P_r$  and the atmospheric pressure  $P_{atm}$  is increased. Therefore, it is likely that a relief valve for failsafe is opened before a desired reference pressure is reached. Once the relief valve is opened, a leak will not be detected. When the setting of valve opening pressure for the relief valve is increased, the pump power is excessively increased and the fuel tank is overloaded. Therefore, the rigidity of the fuel tank must be enhanced to ensure the sufficient strength of the fuel tank.

For the above reasons, it is difficult to enhance the accuracy of leak detection with the above prior arts. Therefore, there is a possibility that the leakage reference values established by CARB and EPA or stricter leakage reference values in the future cannot be met.

To avoid such a situation, a constant-voltage circuit is provided at a position between the battery and the motor pump, the constant-voltage circuit can receive a input voltage which is larger than a predetermined value in a range of varying battery voltage. The battery voltage varies due to the deterioration of the battery. The practical battery voltage varies from 8 volts to 16 volts when a nominal voltage value is 12 volts for automobile. When the difference between the set value of the constant-voltage circuit and the practical battery voltage is larger than a certain value, the redundant electric

energy corresponding to the voltage difference becomes a heat energy of the constant-voltage circuit. The heat generated by the constant-voltage circuit likely affects performance of electric devices such as an alternator and sensors. When a 5 switchover valve and the motor pump are assembled integrally, an output characteristic of the motor pump is likely varied due to the heat generated by the circuit during leak check. The evaluating duration (section C) of the reference pressure and evaluating duration (section D) of evaporated fuel circulation 10 are different from each other. Even if a leak hole and reference orifice have the same diameter, for example,  $\phi 0.5$  mm, a deviation is caused between the reference pressure and a saturation pressure, thus the accuracy of leak inspection deteriorates.

15

#### SUMMARY OF THE INVENTION

The object of the present invention is to provide a leak 20 check device for evaporated fuel purge system which checks a leak by applying or reducing pressure by a motor pump so that the accuracy of leak detection can be enhanced.

A leak check device for evaporated fuel purge system according to the present invention is so constructed to inspect an evaporated fuel purge system for leakage by pressurizing or depressurizing it from a pump through a venting flow path. The 25 leak check device comprises a motor unit which drives the motor for applying or reducing pressure, an in-vehicle power supply, and a voltage control circuit which controls battery voltage

from the in-vehicle power supply to a predetermined voltage and supplies the motor unit with a current. The voltage control circuit is located in an air inlet passage or air outlet passage. The air is introduced into the motor through the air inlet passage.

5

In the evaporated fuel purge system which prevents evaporated fuel produced in the fuel tank of a vehicle from being emitted into the atmosphere, the evaporated fuel is temporarily adsorbed into an adsorption filter, such as a canister, and retains it in the evaporated fuel purge system. The retained evaporated fuel is taken into the air intake system when the internal combustion engine is brought into a predetermined state of operation. In case of common 12V-battery vehicles, the battery voltage of the in-vehicle power supply fluctuates within the range of 8 to 16V.

10

15

The motor unit which drives the pump for pressurizing or depressurizing the evaporated fuel purge system for leak check is fed with input voltage obtained by converting the battery voltage into a predetermined voltage through the voltage control circuit. Even if the battery voltage fluctuates, therefore, the input voltage can be set to, for example, a predetermined voltage within a voltage range in which the battery voltage fluctuates. Thus, variation in the output characteristics of the motor unit and variation in the pump power of the pump driven by the motor unit due to fluctuation in battery voltage can be reduced. As a result, the accuracy of leak detection for inspecting the state of leakage can be

enhanced.

#### BRIEF DESCRIPTION OF THE DRAWINGS

The above and other objects, features and advantages  
5 of the present invention will become more apparent from the  
following detailed description made with reference to the  
accompanying drawings.

FIG. 1 is a schematic block diagram illustrating a leak  
check device for evaporated fuel purge system in the first  
10 embodiment of the present invention.

FIG. 2 is a schematic circuit diagram illustrating a  
drive circuit for a motor pump associated with the leak check  
device in the first embodiment.

FIG. 3 is a schematic diagram illustrating a voltage  
15 control circuit which constitutes the drive circuit for the  
motor pump in FIG. 1.

FIG. 4A is a graph plotting the influences of battery  
voltage fluctuation on motor performance, and FIG. 4B is a graph  
plotting the influences of battery voltage fluctuation on pump  
20 performance.

FIG. 5 is a cross-sectional view of a pump, motor, and  
voltage control circuit showing the arrangement thereof.

FIG. 6 is a graph showing the influences of heat rising  
on pump performance.

25 FIG. 7 is a graph showing the thermal characteristic  
of the voltage control circuit.

FIG. 8 is a schematic circuit diagram of the electric

pump of the second embodiment.

FIG. 9A is a graph plotting the influences of battery voltage fluctuation on motor performance of the third embodiment, and FIG. 9B is a graph plotting the influences of battery voltage fluctuation on pump performance of the third embodiment.

FIG. 10 is a cross sectional view of the leak check module of the fourth embodiment.

FIG. 11A is a graph plotting pressure change characteristics with low battery voltage in the prior art, and FIG. 11B is a graph plotting pressure change characteristics with high battery voltage.

FIG. 12A is a graph plotting the range of pump performance required for producing reference pressure equivalent to a reference leak in the prior art, FIG. 12B is a graph plotting the range of reference pressure with factors of variation associated with pump performance taken into account in the prior art, and FIG. 12C is a graph plotting ideal pump performance.

FIG. 13A is a schematic drive circuit diagram of a DC-motor, and FIG. 13B is a schematic drive circuit diagram of a brushless motor.

FIG. 14A is a graph plotting the influences of battery voltage fluctuation on motor performance in the prior art, and FIG. 14B is a graph plotting the influences of battery voltage fluctuation on pump performance in the prior art.

FIG. 15 is a graph plotting the influence of temperature

of the electric pump on pump performance.

FIG. 16 is a graph showing the pressure characteristic during diagnosing in the prior art.

5

#### DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

##### (First Embodiment)

10

As illustrated in FIG. 1, an evaporated fuel purge system comprises a fuel tank 2, a canister 3 as an adsorption filter which is connected with the fuel tank 2 through a connecting flow path 2a and has a venting flow path 41, and a purge control valve 84 as a vent valve. One end of the vent valve 84 connects to the canister 3 through a valve flow path 82 and the other end of the same connects to the intake system 80 of an internal combustion engine through the valve flow path 82. The canister 3 contains adsorbent 3a such as activated carbon.

15

20

Part of fuel retained in the fuel tank 2 is evaporated, and evaporated fuel is produced in the fuel tank 2. The evaporated fuel is guided into the canister 3 and temporarily adsorbed and accumulated therein. When the purge control valve 84 is opened by air with reduced pressure in the intake system 80, air is taken in through an open flow path 42, the canister 3, and the valve flow path 82. At the same time, the evaporated fuel accumulated in the canister 3 is taken into an inlet pipe 81, and then, supplied into the internal combustion engine to be therein. The evaporated fuel produced in the fuel tank 2 passes through the canister 3 and thereby adsorbed in the canister 3, and air flows out of the canister 3 into the

atmosphere,

The intake system 80 has the inlet pipe 81 connecting to the air intake system of the internal combustion engine. The inlet pipe 81 is provided with a throttle valve 83 for adjusting the flow rate of intake air flowing therein. The valve flow path 82 is open into the inlet pipe 81 downstream or upstream of the throttle valve 83 with respect to intake air.

The fuel tank 2, canister 3, purge control valve 84, connecting flow path 2a, and valve flow path 82 constitute an evaporated fuel purge system 1. The evaporated fuel purge system 1 retains evaporated fuel produced in the fuel tank 2 while the purge control valve 84 is closed. The evaporated fuel purge system 1 thereby prevents the evaporated fuel from being emitted into the atmosphere.

The leak check device is for inspecting the retaining function of the evaporated fuel purge system 1, that is, the state of leakage from the evaporated fuel purge system 1. The leak check device comprises a pump 11 as a pressure source, a motor unit 12 which drives the pump 11, a switchover valve 30, a reference channel 45 for detecting a reference leak, and a pressure sensor 13 as a pressure detecting means for detecting pressure applied by the pump 11.

It is preferable that the pump 11, motor unit 12, switchover valve 30, reference channel 45, and pressure sensor 13 should be disposed above the fuel tank 2 and the canister 3. Thus, liquid fuel or water is prevented from entering these members from the fuel tank 2 or the canister 3. Furthermore,

it is preferable that these members should be integrally assembled into a module. This enhances the workability in assembling the leak check device into the evaporated fuel purge system 1 to inspect the state of leakage from the evaporated  
5 fuel purge system 1.

The venting flow path 41 connects to the fuel tank 2 by way of the canister 3. The venting flow path 41 can be alternately connected to the open flow path 42 and to the pump 11 by switching of the switchover valve 30. The open flow path 10 42 has an open end 42a which is open to the atmosphere. It is preferable that the open end 42a should be provided with a filter for the prevention of ingress of foreign matters such as dust.

The venting flow path 41 is branched to the switchover valve 30 and to the reference channel 45. Thus, when the venting 15 flow path 41 connects to the open flow path 42 by switching of the switchover valve 30, air introduced through the open flow path 42 and a valve-connecting flow path 43 is guided to the reference channel 45. When the venting flow path 41 connects to the pump 11 by switching of the switchover valve 30, the air 20 retained in the venting flow path 41 from which evaporated fuel was adsorbed into the canister 3 can be guided to the pump 11 by way of the valve-connecting flow path 43.

An exhaust flow path 44 lets through air which is discharged from the pump 11 and emitted into the atmosphere 25 through the flow path 42.

The reference channel 45 is provided with a reference orifice 46 as a throttling unit. The reference orifice 46

corresponds to the size of an opening for which leakage of evaporated fuel is acceptable. For example, the CARB and EPA standards provide for the accuracy of detecting leakage of evaporated fuel from an evaporated fuel recovery path, such as  
5 a fuel tank 2, that is, an evaporated fuel purge system 1. The standards require that evaporated fuel leaking through an opening equivalent to  $\phi 0.5$  mm should be capable of being detected. For this reason, in this embodiment, the reference orifice 46 having an opening set to, for example,  $\phi 0.5$  mm or  
10 less is placed in the reference channel 45.

The pump 11 is a positive displacement pump such as a vane pump of known construction. The pump 11 is driven by the motor unit 12 such as a DC motor or brushless motor. The pump 11 and the motor unit 12 constitute an electric motor, and the  
15 electric motor is driven by a current supplied from the in-vehicle power supply. The switchover valve 30 may be any type of electromagnetic valve as long as it is provided with a known switchover valve of three-way valve construction.

The pressure sensor 13 is placed in the valve-connecting flow path 43. The pressure sensor 13 detects pressure in the valve-connecting flow path 43, and outputs a signal corresponding to the pressure to an electronic control unit (ECU) 4 as a controlling means. The ECU 4 comprises a microcomputer having a CPU, a ROM, and a RAM. The ECU 4 is mounted for controlling each component of the internal combustion engine to which the leak check device for evaporated fuel purge system 1 is applied. The ECU 4 is fed with signals  
20  
25

5           outputted from various sensors, including the pressure sensor 13, installed at various parts of the internal combustion engine. According to these inputted signals, the ECU 4 controls various parts of the internal combustion engine in accordance with predetermined control programs recorded in the ROM. The switchover valve 30 is controlled by the ECU 4.

10           The operation of the leak check device is described hereinafter. When a predetermined period of time has passed after the operation of the internal combustion engine is stopped, check is started for leakage of evaporated fuel from the evaporated fuel purge system 1. A period of time required for the temperature of the vehicle to stabilize is set for this predetermined period of time.

15           (1) First, the atmospheric pressure is detected. In this embodiment, the leakage of evaporated fuel from the evaporated fuel purge system 1 is detected based on pressure change. Therefore, the influences of variation in atmospheric pressure due to difference in altitude must be reduced. Consequently, the atmospheric pressure is detected prior to 20 leak check for inspecting the state of leakage. The atmospheric pressure is detected by the pressure sensor 13 placed in the valve-connecting flow path 43. When the electromagnetic drive unit of the switchover valve 30 is not supplied with power, the open flow path 42 connects to the valve-connecting flow path 43 by way of the reference channel 45. Therefore, the pressure 25 in the valve-connecting flow path 43 is substantially identical with the atmospheric pressure.

The pressure detected by the pressure sensor 13 is outputted as a pressure signal to the ECU 4. The pressure signal outputted from the pressure sensor 13 is outputted as voltage ratio, duty ratio, or bit output. Thus, the influences of noise produced by surrounding electrical drive units, such as the electromagnetic drive unit of the switchover valve 30, can be reduced. As a result, the high accuracy of pressure detection can be maintained.

By detecting the atmospheric pressure by the pressure sensor 13, the atmospheric pressure in proximity to the leak check device can be measured. For this reason, the accuracy of detection can be enhanced as compared with cases where the atmospheric pressure is detected by an atmospheric pressure sensor, for example, the sensor of a fuel injector, placed at a distance from the leak check device.

With respect to energization of the motor unit 12, pressure sensor 13, and switchover valve 30, only the pressure sensor 13 is turned on, and power supply to the motor unit 12 and the switchover valve 30 is at a stop (OFF). This state is referred to as "atmospheric pressure detection period A" (for example, section A in FIGS. 11A and 11B). For this reason, the pressure in the valve-connecting flow path 43 detected by the pressure sensor 13 is identical with the atmospheric pressure  $P_{atm}$ .

(2) When the detection of the atmospheric pressure is completed, the altitude at which the vehicle mounted with the leak check device is positioned is computed from the detected

atmospheric pressure. For example, the altitude is determined from a map of correlation between atmospheric pressure and altitude, stored in the ROM of the ECU 4. Based on the determined altitude, various parameters for use in leak check 5 from that time forward are corrected. These processing is carried out by the ECU 4.

When the correction of parameters is completed, power supply to the switchover valve 30 is started (ON). As a result, power supply to the motor unit 12, pressure sensor 13, and 10 switchover valve 30 turns off, on, and on, respectively. This state is referred to as produced evaporated fuel detection state B (for example, section B in FIGS. 11A and 11B). Thus, the open flow path 42 and the valve-connecting flow path 43 is disconnected from each other. Further the venting flow path 15 41 and the valve-connecting flow path 43 are connected to each other.

At this time, the fuel tank 2 is isolated from the atmosphere without fail by a check valve 100, which does not open until a preset pressure is reached. When fuel is 20 evaporated in the fuel tank 2 and evaporated fuel is produced therein, the pressure in the fuel tank 2 becomes higher than the outside pressure. Therefore, the pressure in the valve-connecting flow path 43 detected by the pressure sensor 13 is slightly increased. To the contrary, when the fuel vapor 25 temperature lowers and evaporated fuel is liquefied, the pressure in the fuel tank 2 becomes lower than the outside pressure. Therefore, the pressure in the valve-connecting

flow path 43 detected by the pressure sensor 13 slightly drops.

(3) When it is detected that pressure change due to the production of evaporated fuel in the fuel tank 2 is a predetermined value or less, power supply to the switchover valve 30 is interrupted (OFF). Further, power supply to the motor unit 12 is started (ON). As a result, power supply to the motor unit 12, pressure sensor 13, and switchover valve 30 turns on, on and off, respectively. This state is referred to as "reference leak detection state C" (for example, section C in FIGS. 11A and 11B).

Thus, the pump 1 is driven, and the valve-connecting flow path 43 is depressurized. As a result, the air in the open flow path 42 flows into the reference channel 45 by way of the reference orifice 46. Since the air flow into the reference channel 45 is throttled by the reference orifice 46, the pressure in the reference channel 45 is lowered. The reference orifice 46 is set to a predetermined size. Therefore, the pressure in the reference channel 45 drops until a predetermined pressure is reached, and then becomes constant. At this time, the detected predetermined pressure in the reference channel 45 is stored in the RAM of the ECU 4 as the reference pressure  $Pr$ .

(4) When the detection of reference pressure  $Pr$  is completed, power supply to the switchover valve 30 is resumed. As a result, power supply to the motor unit 12, pressure sensor 13, and switchover valve 30 turns on, on and on, respectively. This state is referred to as "internal pressure detection state D"

(for example, section D in FIGS. 11A and 11B). Thus, the venting flow path 41 and the valve-connecting flow path 43 are connected to each other. Further, the open flow path 42 and the valve-connecting flow path 43 are disconnected from each other.

5 As a result, the fuel tank 2 and the reference channel 45 are connected to each other. Therefore, the pressure in the reference channel 45 approaches the atmospheric pressure once.

10 As a result of the motor unit 12 being energized, the operation of the pump 11 is started. The pump 11 may be continuously operated following the reference leak detection state C. When the pump 11 has been operated, the internal pressure in the fuel tank 2 is reduced with time. It may be referred to the pressure change characteristics in section D in FIGS. 10A and 10B, for example. At this time, the pressure 15 in the valve-connecting flow path 43 detected by the pressure sensor 13 is identical with the internal pressure in the fuel tank 2 because the valve-connecting flow path 43 connects to the fuel tank 2.

20 At this time, based on the pressure change characteristics in section D according to the detection by the pressure sensor 13, the state of leakage from the evaporated fuel purge system 1, including the fuel tank 2, is determined 15 as follows.

25 When the internal pressure in the valve-connecting flow path 43, that is, the fuel tank 2 falls below the reference pressure  $P_r$  with the operation of the pump 11, the state of leakage from the fuel tank 2, that is, the evaporated fuel purge

system 1 is determined acceptable. When the internal pressure in the fuel tank 2 is lower than the reference pressure  $P_r$ , the ingress of air into the fuel tank 2, that is, the evaporated fuel purge system 1 from the outside is not present or is only slightly present. This means that the hermeticity of the evaporated fuel purge system 1 is sufficiently attained. For this reason, evaporated fuel produced in the fuel tank 2 is not emitted or is only slightly emitted to the outside. The leakage of evaporated fuel, that is, the state of leakage from the evaporated fuel purge system 1 is determined acceptable.

Meanwhile, when the internal pressure in the fuel tank 2 is not reduced to the reference pressure  $P_r$ , the state of leakage from the evaporated fuel purge system 1 is determined in excess of the acceptable level. When the internal pressure in the fuel tank 2 is not reduced to the reference pressure  $P_r$ , it is suspected that outside air has entered due to depressurization in the fuel tank 2, that is, the evaporated fuel purge system 1. For this reason, when evaporated fuel is produced in the fuel tank 2, it is suspected that the evaporated fuel is being emitted to the outside at any point of the evaporated fuel purge system 1 including the fuel tank 2. Thus, when the internal pressure in the fuel tank 2 is not reduced to the reference pressure  $P_r$ , the leakage of evaporated fuel, that is, the state of leakage from the evaporated fuel purge system 1 is determined in excess of the acceptable level.

When the state of leakage from the evaporated fuel purge system 1 is determined in excess of the acceptable level, some

measures are taken. For example, at the next time of the operation of the internal combustion engine, an indicating device informs the driver and other occupants of the vehicle of a leak of evaporated fuel in the evaporated fuel purge system 5. Such indicating means include lighting of an alarm lamp provided on the indicator panel, such as meter panel (not shown).

When the internal pressure in the fuel tank 2 is substantially identical with the reference pressure  $P_r$ , there 10 is a leak of evaporated fuel equivalent to the reference orifice 46 from the evaporated fuel purge system 1. In this case as well, the leakage of evaporated fuel, that is, the state of leakage from the evaporated fuel purge system 1 is determined in excess of the acceptable level.

15 (5) When the inspection on the state of leakage from the evaporated fuel purge system 1 by leak check is completed, power supply to the motor unit 12 and the switchover valve 30 is interrupted (OFF). As a result, power supply to the motor unit 12, pressure sensor 13, and switchover valve 30 turns off, on 20 and off, respectively. This state is referred to as "determination completion state E" (for example, section E in FIGS. 11A and 11B). Thus, the pressure in the valve-connecting flow path 43 and the reference channel 45 is restored to the atmospheric pressure. The ECU 4 confirms that the pressure in 25 the valve-connecting flow path 43 has been restored to the atmospheric pressure. Then, the ECU 4 stops the operation of the pressure sensor 13 to terminate leak check on the evaporated

fuel purge system 1.

In case of evaporated fuel purge system which prevents evaporated fuel produced in the fuel tank 2 of the vehicle from being emitted into the atmosphere, a leak check device is also mounted on the vehicle. This leak check device is for, when the state of leakage of evaporated fuel exceeds the acceptable level, informing the occupants and the like of that. For this reason, as a power source for supplying a current to the motor unit 12 which drives the pump 11, an in-vehicle power supply (battery not shown) is used. The battery voltage of a battery may fluctuate due to deterioration or the like. For example, in common 12V-battery vehicles, the battery voltage fluctuates within the range of 8 to 16V.

In the electrical configurations of the motor units of the conventional motor pumps, illustrated in FIGS. 13A and 13B, as input voltage for supplying the motor units with a current, battery voltage +B is applied to the motor units. With such prior art, when the battery voltage fluctuates due to deterioration or the like, the driving voltage proportionally fluctuates. This can result in change in the motor performance itself of the motor pump, that is, the motor unit 12 or the pump performance itself of the pump 11.

In FIG. 13A, the battery voltage (+B) is applied to the input stage of the motor unit, such as DC motor 12. In FIG. 13B, the motor unit, such as brushless motor 12, has a motor drive circuit (motor drive IC) 5, and the battery voltage (+B) is applied to the input side of the motor drive IC 5. The motor

drive IC 5 changes the positions of passing a current through coils (not shown). The motor drive IC 5 thereby controls the driving of the motor 5 which rotatably drives a rotator (not shown) and has no electrical contacts.

5 Referring to FIGS. 11A, 11B, 12A, 12B, 12C, and 13A illustrating comparative examples, the range of variation in the motor performance of the motor unit 12 and in the pump performance of the pump 11 will be described. To the input stage of the motor unit 12 of the motor pump in the comparative examples, 10 the battery voltage is applied (FIG. 13A). The procedures for operating the leak check device in the comparative examples have been described above in contrast with this embodiment, and the description thereof will be omitted. When the battery voltage inputted to the motor unit 12 is low, the output characteristics 15 of the motor unit 12 are lowered, which results in the lowered pump performance of the pump 11.

As illustrated in FIG. 11A, the pressure difference between the inside and the outside of the evaporated fuel purge system 1, that is, the pressure difference between reference 20 pressure  $P_r$  and atmospheric pressure  $P_{atm}$  is reduced. For this reason, the differences are reduced between various pressure characteristics detected in section D: pressure characteristics wherein the state of leakage is acceptable; pressure characteristics wherein the state of leakage is substantially the same as in the reference orifice 46; and 25 pressure characteristics wherein the state of leakage is in excess of the acceptable level. As a result, there is a

possibility that the accuracy of leak detection is degraded.

The leak detection is for determining in which state of leakage the size of a leaking hole in the evaporated fuel purge system 1, determined from internal pressure change in section D, is. Meanwhile, when the battery voltage inputted to the motor unit 12 is high, there is a worry that the pressure difference between reference pressure  $P_r$  and atmospheric pressure  $P_{atm}$  becomes too large, as illustrated in FIG. 11B. When the pressure difference is too large, the magnitude of the negative pressure of the reference pressure is also increased. Therefore, the relief valve for failsafe is opened before the reference pressure is reached and a leak cannot be detected.

Referring to FIGS. 12A to 12C, the influences of variation in pump performance on the reference pressure  $P_r$  obtained by the reference orifice 46 will be described below. FIGS. 12A to 12C are graphs which plots the reference pressure obtained by the reference orifice and the range of the pump performance in the comparative examples. FIG. 12A is a graph plotting the range of pump performance required for producing reference pressure equivalent to a reference leak. FIG. 12B is a graph plotting the range of reference pressure with factors of variation associated with pump performance taken into account. FIG. 12C is a graph plotting ideal pump performance. In FIGS. 12A to 12C, the horizontal axes represent the magnitude of pressure, and the vertical axes represent flow rate.

The pump performance of the pump 11 is in proportion to the motor performance of a motor unit 12 for driving the pump

11. In the motor unit 12, such as a DC motor and a brushless motor, the rotational speed and the motor torque are correlated to each other. The rotational speed is maximized under no load, and is reduced with increase in motor torque. The torque which zeroes the rotational speed is a holding torque. As described above, the pump performance is in proportion to the motor performance.

As illustrated in FIG. 12A, under no load, that is, when the produced pressure  $P$  is zero, the flow rate  $Q$  is maximized. The flow rate  $Q$  is lowered with increase in produced pressure  $P$ , and the pressure which zeros the flow rate is shutoff pressure. The characteristics (reference flow) of the reference orifice 46 is as plotted in FIGS. 12A to 12C. At the intersection point where the characteristics of the pump and the characteristics of the reference orifice 46 intersect each other in FIG. 12A, reference pressure is produced by the reference orifice 46.

First, variation (VAR) in the pressure  $P$  in the evaporated fuel purge system 1 detected by leak check is considered with respect to the upper limit and the lower limit with the reference pressure taken as the center. When the produced pressure  $P$  is too high, the relief valve for failsafe is opened. Therefore, the upper limit of variation in the pressure in the evaporated fuel purge system 1 must be considered that the valve opening pressure of the relief valve will not be exceeded. For this reason, the range of variation in pump performance must be controlled so that the reference pressure for causing a reference leak for inspecting the state

of leakage from the evaporated fuel purge system 1 will fall within the range A in FIG. 12A. That is, the range A is the range of required reference pressure  $P_r$ .

5 There are various possible factors of variation in pump performance. Such possible factors include variation in, for example, the motor unit 12 due to pump driving source; variation in, for example, battery voltage due to applied voltage for driving the motor unit 12; and the dimensional tolerance (TOL) of the pump 11 due to the suction volume per rotation of the  
10 pump 11. Of these factors of variation, the most primary one is battery voltage (8 to 16V for 12V-battery vehicles).

15 The reference pressures resulting from various factors of variation in the motor pump constituting the leak check device in this embodiment are as plotted in FIG. 12B. A plurality of pump characteristics, indicated by dotted lines, represent variations due to respective factors. The factors of variations are plotted as are integrated along the pump characteristics indicated by a solid line. According to FIG. 20 12B, the reference pressures caused by these factors of variation exceed and deviate out of the required range. The hatched areas represent variation in pump performance due to variation in applied voltage.

25 When the pump 11 is a positive displacement pump, such as a vane pump, it can be made unnecessary to take variation in applied voltage, which is the most primary factor, into account. This is done by controlling variation in applied voltage, that is, input voltage which supplies the motor unit

12 with a current to within a certain width of voltage. For example, the pump characteristics can be confined within a required range by carrying out pump chamber adjustment when building in a pump (FIG. 12C).

5           The pump characteristics can be confined within a required range by carrying out pump chamber adjustment when building in a pump, as illustrated in FIG. 12C. However, there is substantially no margin for this. On this account, variation 10 in applied voltage has great influences on the performance of a pump regardless of whether the pump performance is adjusted or not. Therefore, variation in applied voltage must be eliminated. Adjustment of pump performance can be easily effected by adjusting variation in the motor unit 12 as the pump driving source or the pump 11 (mainly variation in the 15 dimensional tolerance of the valve).

For this reason, this embodiment is provided with a voltage control circuit (constant voltage circuit) 7, as illustrated in FIG. 2. The constant voltage circuit 7 controls the battery voltage from the battery to a predetermined voltage, 20 and supplies the motor unit 12 with a current. Thus, the motor unit 12 is fed with an input voltage obtained by converting the battery voltage into the predetermined voltage, by the constant voltage circuit 7. Therefore, even if the battery voltage fluctuates, the input voltage to the motor unit 12 can be regulated to the predetermined voltage within the voltage range 25 within which the battery voltage fluctuates. Therefore, variation in the output characteristics of the motor unit 12

due to fluctuation in battery voltage can be reduced (FIG. 4A).

Furthermore, variation in the pump performance of the pump 11, which is driven by the motor unit 12, can be reduced as shown in FIG. 4B. In this embodiment, the predetermined value of input voltage controlled by the constant voltage circuit 7 is set to 10V, as illustrated in FIG. 4A. Thus, variation in the performance of the motor unit 12, illustrated in FIG. 4A, can be minimized as compared with the prior art illustrated in FIG. 14A, wherein the battery voltage is supplied as input voltage to the motor unit 12. As a result, variation in the pump performance of the pump 11 illustrated in FIG. 4B can be minimized as compared with the prior art illustrated in FIG. 14B.

Here, the battery voltage required for actuating a starter (not shown) as the starting device of the internal combustion engine is approximately 11V or above. For this reason, the battery is charged to some degree beforehand to enhance the battery voltage more than required for driving the starter by a battery charger such as an alternator. For the alternator for use in 12V-battery vehicles, the charging voltage is approximately 13V.

For this reason, in this embodiment, the above predetermined voltage is set within the range of 10V or less. That is, the predetermined voltage is regulated to be less than a voltage required for driving the starter. This takes into account deterioration of the battery which occurs when the vehicle is left standing for the stabilization of temperature,

before leak detection by the leak check device. Thus, the accuracy of leak detection is enhanced. Further, the input voltage can be set to the range of 10V or less. In the voltage range within which the battery voltage fluctuates, this range of 10V or less is the region where the input voltage can be easily set to the predetermined voltage by the constant voltage circuit 7.

When the battery is caused to supply a current to the starter and the starter is thereby actuated to start the internal combustion engine, a load is applied to the battery. In this case, the minimum voltage of the battery may drop from approximately 8V to 6V or so. When the setting of the lower limit value of the predetermined value of input voltage controlled by the constant voltage circuit 7 is excessively lowered, a problem may arise. When the battery voltage is higher than the lower limit value, the surplus battery voltage is wastefully converted into heat energy by heat generation from the constant voltage circuit 7. Therefore, it is preferable that the lower limit of the range of input voltage should be 8V or above.

Further, in this embodiment, the constant voltage circuit 7 comprises a Zener diode 71 and a semiconductor device 72, as illustrated in FIG. 2. Thus, only by adding the Zener diode 71 and the semiconductor device 72, the constant voltage circuit 7 for controlling input voltage can control the input voltage to a predetermined voltage regardless of whether the motor unit 12 is under a load or without load. As described

above, the constant voltage circuit 7 is constituted with only the Zener diode 71 and the semiconductor device 72 added. Therefore, the accuracy of leak detection is enhanced, and further the constant voltage circuit 7 can be provided at low 5 cost.

In this embodiment, the constant voltage circuit 7 is placed between the battery and the motor unit 12. However, as illustrated in FIG. 3, the constant voltage circuit 7 may be placed between the motor unit 12 and the ECU 4 which is supplied 10 with the battery voltage from the battery. Since the constant voltage circuit 7 is constituted with only the Zener diode 71 and the semiconductor device 72 added, it may be installed and disposed at the input stage at the end of the motor unit 12.

As shown in FIG.2 , the voltage circuit 7 is located 15 in the air flow.

In case of common 12V-battery vehicles, the battery voltage of the in-vehicle power supply fluctuates within the range of 8 to 16V and the practical voltage is approximately 13V. When the difference between the practical voltage and the 20 set voltage of the circuit 7 is larger than a certain value , for example set voltage is 10V and the practical voltage is 13v, the redundant electric energy corresponding to the voltage difference generates heat in the constant set voltage circuit 7. The heat generated by the constant-voltage circuit likely 25 affects performance of electric devices such as an alternator and a pressure sensor 13. There is a possibility that the reference pressure caused by the reference orifice at the time

of motor starting and at the time of the leak checking are different as shown in FIG. 15. The heat of the constant voltage circuit causes such a deviation. As shown in FIG.16, deviation is caused due to the pomp characteristics change. The saturated pressure is lager than the reference pressure. It would be judged that the leak hole and the reference orifice have the same size(  $\phi$  0.5 or less) even though it should be judged abnormal.

On the contrary, in this embodiment, the constant voltage circuit 7 is located in the airflow space or the air passage, and the circuit 7 is cooled by the air to avoid temperature increasing thereof. Since the heat increasing of the circuit 7 is restrained by the air, the change of pomp characteristic due to the heat of the motor unit 12 is restrained. Thus, the accuracy of detecting leak check is enhanced. The constant voltage circuit 7 can be located in another place where the air flows such as the air outlet passage.

In this embodiment, as shown in FIG.5, the constant voltage circuit 7 is located in the air outlet passage 44 through which the air flows from the air outlet 15 of the pomp 11.

The constant voltage circuit 7 has circuit components such as a Zener diode 71 and a semiconductor 72 on a circuit board. Whole of the circuit board or a part of the circuit board is located in the air outlet passage 44 in such a manner that the circuit board disturbs the airflow. In FIG.6 and FIG. 7, a solid line represents the characteristic of the present embodiment and a broken line represents the conventional

characteristic. An alternate long and short dashed lines in FIG.6 represents the characteristic wherein there is no temperature rise in the constant voltage circuit 7. Since the temperature rise in the circuit 7 is restrained, the deleterious effect of heat to the motor unit 12 is reduced as compared with the conventional one. In FIG.7, a solid line represents the present embodiment and a broken line represents the conventional circuit.

Since the pump 11 for reducing the pressure to check the fuel leak is used for generating the airflow, no additional pump for generating the airflow is necessary. Therefore, the leak check device is provided in low cost.

In this embodiment, the pump 11 is a pressure reducing pump, however, a pressure applying pump is also usable. When the pressure applying pump is used, the constant voltage circuit 7 is located in the inlet passage through which the air is introduced into a inlet port 14.

In this embodiment described above, the influences of fluctuations in the battery voltage on pump performance is restricted by the constant voltage circuit 7. Therefore, when a reference leak obtained by the reference orifice 46 and a leak from the evaporated fuel purge system 1 are detected and a difference from an actual leak is measured, the accuracy of leak detection can be also enhanced. Thus, the influences of fluctuation in battery voltage on pump performance are prevented. Further, the reference leak and the actual state of leakage are alternately measured using the switchover valve

30. Therefore, even if simultaneous measurement cannot be made, stable measurement can be carried out regardless of the presence or absence of fluctuation in battery voltage.

Further, in the above embodiment, the influences of fluctuation in the battery voltage on the motor performance of the motor unit 12 and the pump performance of the pump 11 are prevented by the constant voltage circuit 7. Therefore, other methods than the method of directly detecting pressure characteristics by a pressure detecting device such as the pressure sensor 13 can be adopted to detect the state of leakage. For example, the state of operation of the motor unit 12 which drives the pump 11 can be detected to indirectly detect pressure characteristics. In this case, operation characteristic values such as power consumption, rotational speed or electric current value are detected. In this case as well, the accuracy of detecting the state of leakage can be enhanced.

When the constant voltage circuit 7 is integrated with the motor unit 12 as a module, the motor unit 12 is cooled through the circuit board by the air flowing in the air passage. The air flowing to the motor unit 12 is divided by the circuit board as a baffle plate.

Further, in the above embodiment, the leak check device is actuated according to a certain procedure: prior to the depressurization of the evaporated fuel purge system 1, including the fuel tank 2, the pressure of mixed gas which passed through the valve-connecting flow path 43 is detected. Thus, leak check on the evaporated fuel purge system 1 can be carried

out regardless of ambient conditions including altitude (atmospheric pressure), temperature and humidity. As a result, the accuracy of leak detection can be enhanced.

Further, in the above embodiment, the pressure in the valve-connecting flow path 43 connecting to the fuel tank 2, that is, the evaporated fuel purge system 1 is directly detected by the pressure sensor 13. For this reason, the accuracy of leak detection can be enhanced as compared with cases where the pressure in the evaporated fuel purge system 1 is indirectly detected from operation characteristic values such as the electric current value of the motor unit 12.

Further, in the above embodiment, leak detection is carried out by reducing the pressure in the evaporated fuel purge system 1. Thereby, the state of leakage of evaporated fuel from the evaporated fuel purge system 1 is inspected. For this reason, mixed gas is prevented from being emitted to the outside of the evaporated fuel purge system 1 during leak check, and the environment is protected.

(Second Embodiment)

As described above, in the first embodiment, the constant voltage circuit 7 is connected to the input stage of the motor unit 12 for controlling the input voltage which supplies the motor unit 12 with a current to the predetermined voltage. In the second embodiment, the constant voltage circuit 7 is connected to the motor drive IC 5 instead of the motor unit 12, as illustrated in FIG. 8. Thus, as a motor unit 12 for driving the pump 12, a brushless motor which has no

electrical contacts and has no slidable contact portions can be used. The motor unit 12 may be a DC motor or a brushless motor having the motor drive IC 5. In either case, input voltage which supplies the motor unit 12 with a current can be controlled by the constant voltage circuit 7. Even if evaporated fuel from the evaporated fuel purge system 1 sweeps through the canister 3 and enters the pump 11 and the motor unit 12, local wear is prevented, and the life of the leak check device can be lengthened.

10 (Third embodiment)

The predetermined voltage to which the input voltage is controlled by the constant voltage circuit 7 is not limited to that in the first embodiment. In the third embodiment, the input voltage is controlled within the predetermined voltage range illustrated in FIGS. 9A and 9B. In this embodiment, changes from 8V to 10V is allowed as the range of input voltage controlled by the constant voltage circuit 7, as illustrated in FIG. 9A. In FIGS. 9A and 9B, the thick solid lines indicate characteristics with the input voltage being 10V, the upper limit, and the thin solid lines indicate characteristics with the input voltage being 8V, the lower limit.

Thus, variation VAR in the performance of the motor unit 12 illustrated in FIG. 9A can be reduced as compared with the prior art illustrated in FIG. 14A. The amount of this reduction is equivalent to the margin of fluctuation in the input voltage which is reduced from 8 to 16V to 8 to 10V. As a result, variation VAR in the pump performance of the pump 11 illustrated

in FIG. 9B, can be reduced as compared with the prior art illustrated in FIG. 14B. This width of input voltage setting is not limited to 8 to 10V, and may be other values, for example, 9 to 10V, or 9.5 to 10V.

5           Further, relatively wide latitude can be allowed as the set value of input voltage controlled by the constant voltage circuit 7. Thus, high accuracy is not required for the set value of input voltage, and thus a relatively inexpensive constant voltage circuit 7 can be used.

10           When the internal combustion engine is started, an electric current is supplied to a starter from the battery. Due to the load of the battery, the minimum voltage of the battery is likely to vary from 8V to 6V approximately. When the input voltage or minimum voltage controlled by the constant voltage circuit 7 is set low value, and when the supplied voltage is higher than the set value, the surplus battery voltage is converted into the heat energy as a heat of the constant voltage circuit 7. Thus, it is preferable that the minimum voltage is set 8V or more.

15

20           (Fourth embodiment)

          In a fourth embodiment, of the constituent members of the leak check device described as the first embodiment, those disposed in the dotted line in FIG. 2 are integrally assembled into a module. Specifically, the leak check module 10 is constructed as illustrated in FIG. 10. The leak check module 10 comprises a housing 20, a pump 11, a motor unit 12, a switchover valve 30, a pressure sensor 13 and a constant voltage

circuit.

The housing 20 houses the pump 11, motor unit 12 and switchover valve 30. The housing 20 comprises a pump chamber 21 for housing the pump 11 and a valve chamber 22 for housing the switchover valve 30. The housing 20 further comprises a venting flow path 41, an open flow path 42, a valve-connecting flow path 43 and an exhaust flow path 44. The venting flow path 41 runs from the valve chamber 22 in the housing 20 to the fuel tank 2 by way of the canister 3. The open flow path 42 runs from the valve chamber 22 to the open end 42a. The valve-connecting flow path 43 connects the pump chamber 21 and the valve chamber 22.

The valve-connecting flow path 43 is provided with a pressure introducing passage 43a which is branched from the valve-connecting flow path 43. At the upper end of the pressure introducing passage 43a, the pressure sensor 13 is housed as is fixed on the inner circumferential surface of the housing 20. Thus, the pressure in the valve-connecting flow path 43 and the reference channel 45 is detected by the pressure sensor 13 through the pressure introducing passage 43a.

The exhaust flow path 44 connects the pump chamber 21 and the open flow path 42 through the valve chamber 22. The valve-connecting flow path 43 and the reference channel 45 are branched from each other in the direction of the axis of the switchover valve 30. The reference channel 45 is open toward the venting flow path 41 or downward.

The pump 11 is housed in the pump chamber 21, and has

an admission port 14 and an exhaust port 15. The admission port 14 is disposed in the valve-connecting flow path 43, and the exhaust port 15 is disposed in the pump chamber 21. When the pump 11 is driven by the motor unit 12, air in the valve-connecting flow path 43 is taken into the pump 11. A check valve 48 is placed between the admission port 14 and the valve-connecting flow path 43.

As illustrated in FIG. 10, the switchover valve 30 comprises a valve body 31 and an electromagnetic drive unit 60. The electromagnetic drive unit 60 comprises a moving member 50, a coil 61, a core 62, a spring 63 and the like.

The valve body 31 is housed in the valve chamber 22. The valve body 31 has a first valve seat 32 on the venting flow path 41 side. The valve member 51 attached to the moving member 50 can abut the first valve seat 32. With movement of the moving member 50, the valve member 51 is abutted against the first valve seat 32. As a result, the venting flow path 41 and the open flow path 42 are disconnected from each other.

Further, the venting flow path 41 and the valve-connecting flow path 43 are connected to each other. The moving member 50 has an abutting portion 52, and the abutting portion 52 can be abutted against a second valve seat 33 which is formed at the end of the valve-connecting flow path 43 on the valve chamber 22 side. With movement of the moving member 50, the abutting portion 52 is abutted against the second valve seat 33. As a result, the venting flow path 41 and the open flow path 42 are connected to each other, and further the venting

flow path 41 and open flow path 42 and the valve-connecting flow path 43 are disconnected from each other.

The moving member 50 is driven by electro magnetic force from the coil 61 constituting the electromagnetic drive unit 60 and biasing force from the spring 63 constituting the same. The electromagnetic drive unit 60 has the coil 61 electrically connected with the ECU 4. By passing a current through the coil 61, a magnetic field is produced in the core 62, which attracts the moving member 50 upward in the axial direction. The moving member 50 is kept energized by the spring 63 in the direction opposite the direction of attraction by electromagnetic force from the coil 61.

When the passage of a current through the coil 61 is at a stop, the moving member 50 is moved downward by biasing force from the spring 63, as illustrated in FIG.10, and the abutting portion 52 is in contact with the second valve seat 33. For this reason, the venting flow path 41 and the open flow path 42 are connected to each other, and further the venting flow path 41 and open flow path 42 and the valve-connecting flow path 43 are connected to each other through the reference channel 45.

The constant voltage circuit 7 is electrically connected with the input stage at the end of the motor unit 12, and is fixed on the motor unit 12. Thus, the constant voltage circuit 7 can be also modularized, and the assembling workability is enhanced. For example, vehicles for a place of destination where leakage standards are different can be coped with just

by building only a leak check module 10 meeting the leakage standards in the fuel tank 2, that is, the evaporated fuel purge system 1.

5 The constant voltage circuit 7 is constructed on the circuit board having circuit components such as Zener diode 71 and a semiconductor device 72. Whole of the circuit board or a part of the circuit board is located in the exhaust flow path 44. The air discharged from the outlet 15 flows into the exhaust flow path 44 through the pump chamber 21. Thus, it is possible 10 that the constant voltage circuit 7 is cooled by the air directly without providing another cooling device.

15 In this embodiment, the pressure sensor 13 is located on an upstream of the pressure introducing passage 43a, and the constant voltage circuit 7 is located in the pump chamber 21. Since the pressure sensor 13 is located upper portion than the constant voltage circuit 7, influence of heat from the constant voltage circuit 7 on the pressure sensor 13 is prevented. The error of the pressure sensor 13 is restrained and the characteristic of the pressure sensor 13 is stable. The accuracy 20 of leak check is enhanced.

25 The pressure introducing passage 43a is a part of the valve-connecting flow path 43. Both of the pressure introducing passage 43a and the valve-connecting flow path 43 constitute an air inlet passage. The pump chamber 21 is communicated with the open flow path 42 through the exhaust flow path 44. Both of the pump chamber 21 and the exhaust flow path 44 constitute an air outlet passage.

Referring to FIG.10, the air outlet passage formed in the pump chamber 21 comprises a first air path and a second air path. The first air path is formed by the inner surface of the pump chamber 21 and outer surface of the pump 11. The second air path is formed by the inner surface of a housing and side surface of the motor unit 21. Since the first air path is narrower than the second air path, a velocity of air flowing in the first air path is higher than that of air flowing in the second air path. The constant voltage circuit 7 is located at the end of the motor unit 12 in the second air path. Since the constant voltage circuit 7 is located in the narrowest path, the air having highest velocity is introduced into the circuit 7. Thus, the temperature of the circuit 7 is kept within a certain range efficiently.

As shown in FIG.10, the electric motor and switchover valve 30 are arranged in such a manner that axes of the electric motor and the switchover valve 30 are approximately parallel and adjacent to each other. The open flow path 42 in which an air flows from the pump chamber 21 via the exhaust flow path 44 is formed by the side surface of the switchover valve 30 and inner surface of the valve chamber 22. The open flow path 42 is relatively small in cross- sectional area. The passage having a large cross-sectional area, i.e. the second air flow passage and the air outlet passage are formed in a middle portion of the whole of the air passage. Thus, the leak check module is compact as a whole, and the electric pump and the switchover valve 30 are assembled in a direction of axes thereof so that

the assembling process is simplified.

The above embodiments have been described based on cases where a 12V-battery whose battery voltage fluctuates within the range of 8 to 16V is used as an in-vehicle power supply. However, 5 the specifications for battery are not limited to a nominal voltage of 12V. There are a variety of batteries different in nominal voltage for various applications. Therefore, the voltage of a current supplied from the constant voltage circuit 7 to the motor unit 12 is preferably 84% or below of the nominal 10 voltage value of battery voltage. For 24V-battery used as, for example, battery for trucks, the voltage is preferably 20V or below.

In the embodiments described above, since the circuit board including the constant voltage circuit 7 and the motor unit 12 needs no additional radiation member, upsizing of the 15 element around the circuit board is prevented. In a result, the constant voltage circuit 7 is assembled without upsizing of the leak check module 10.

The location of the pressure sensor 13 is not limited 20 in the pressure introducing passage 43a but also in the valve-connecting flow path 43. The pressure sensor 13 can be located in the upstream of the constant voltage circuit 7 as long as the pressure sensor 13 is located in the air inlet 25 passage.

When the pump 11 is a pressurizing pump, the pressure 25 sensor 13 and the constant voltage circuit 7 are located in the air outlet passage and in the air inlet passage respectively.

When the constant voltage circuit 7 is located in the air inlet passage or the air outlet passage where the pressure sensor 13 is disposed, it is preferable that the pressure sensor 13 is located in the upstream of the constant voltage circuit 7 so as to avoid the heat deleterious effect on the pressure sensor 13.